

# Test of CWA's Experimental Profile-Dependent Radio Occultation Observation Error Model Using the ROMEX Data



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## Introduction

- The observation-profile-dependent nature of the observation errors of the RO data has posed challenges to their quality control (QC) and/or observation error specification.
- Local Spectral Width (LSW)** is a measure of the RO bending angle data uncertainty. Several studies have pursued the use of the LSW information to improve the QC or to construct observation error models.
  - Liu et al. (2018): Use LSW for QC. (discarding data with large LSW values)
  - Zhang et al. (2023), Sjoberg et al. (2023), Li et al. (2024), and [this study](#): Use LSW to formulate an observation error model. All of these studies share a similar concept but formulate the observation error models in different ways. ~ "continuous" (or "nonlinear") QC

## Observation error model with LSW

- Assume the RO bending angle observation error variance is composed of a "dynamic" term and the other "quasi-static" term.

The latter is not profile-dependent, but can be a function of height and latitude (or other parameters):

$$\sigma^2 = \sigma_{\text{dyn}}^2 + \sigma_{\text{other}}^2 \quad (1)$$

- Take long-term average of (1) for each height and latitude bin:  $\sigma_{\text{static}}^2$  : Static observation error by traditional methods (e.g., Desroziers et al. 2005) (for each height and latitude bin)

$$\sigma_{\text{static}}^2 \equiv \overline{\sigma^2} = \overline{\sigma_{\text{dyn}}^2} + \sigma_{\text{other}}^2 \quad (2)$$

- (1) - (2)  $\rightarrow \sigma^2 - \sigma_{\text{static}}^2 = \sigma_{\text{dyn}}^2 - \overline{\sigma_{\text{dyn}}^2}$
- $\rightarrow \sigma^2 = \sigma_{\text{static}}^2 + \sigma_{\text{dyn}}^2 - \overline{\sigma_{\text{dyn}}^2}$  (3)

Let  $\sigma_{\text{dyn, clim}} \equiv \sqrt{\overline{\sigma_{\text{dyn}}^2}}$ :

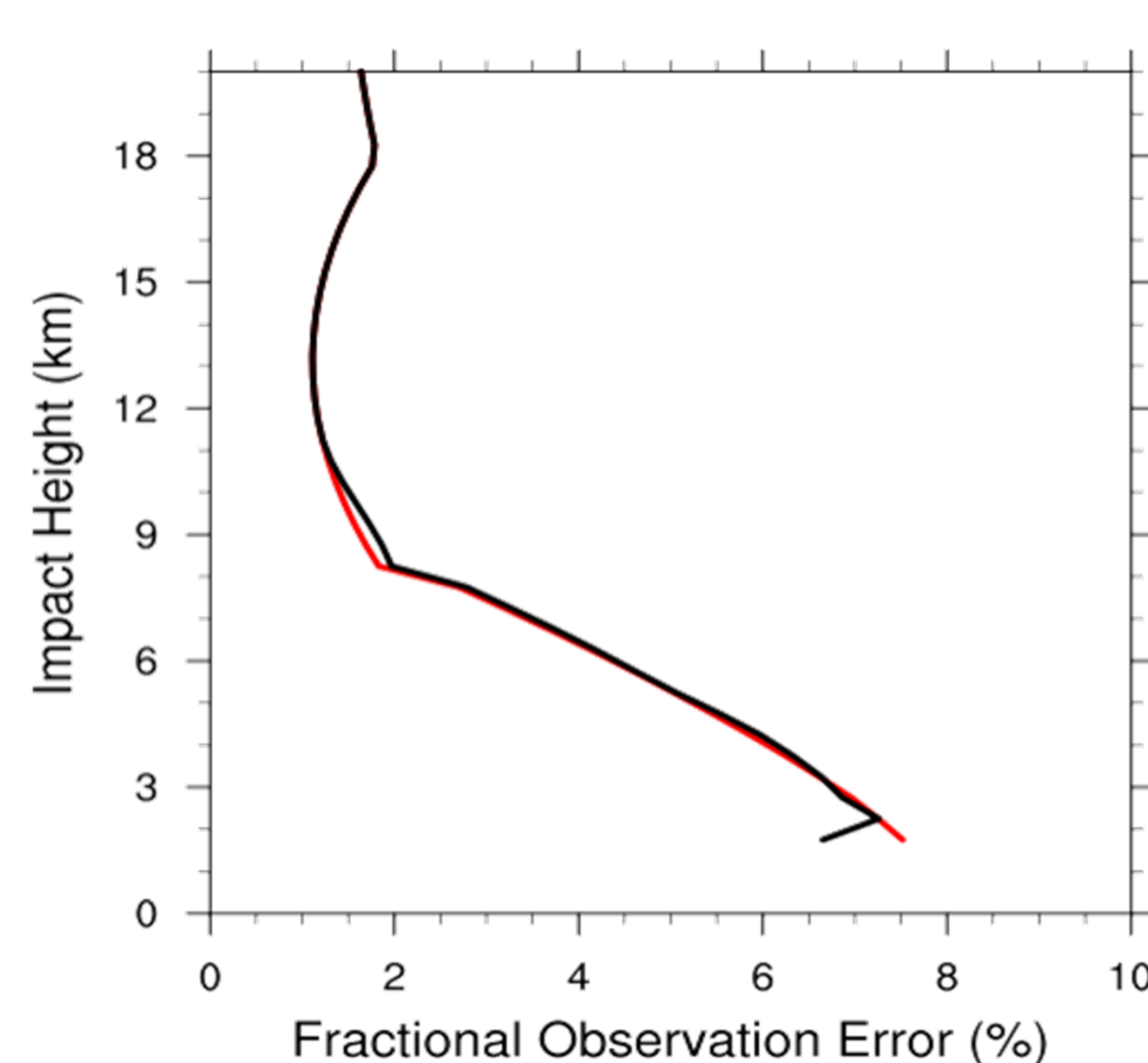
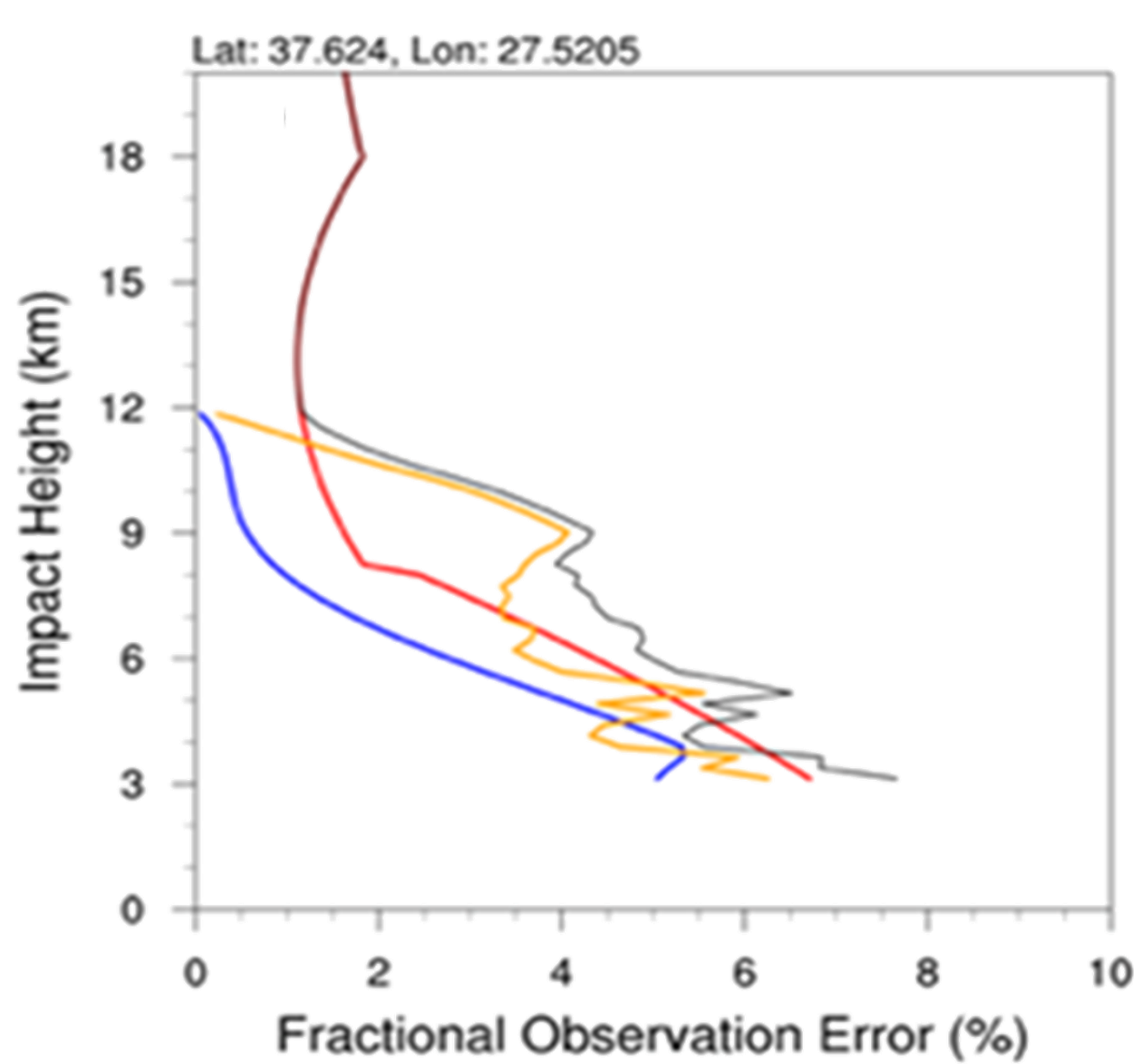
$$\rightarrow \sigma = \sqrt{\sigma_{\text{static}}^2 + \sigma_{\text{dyn}}^2 - \sigma_{\text{dyn, clim}}^2} \quad (4)$$

- $\sigma_{\text{dyn}}$  : Dynamic observation error  $\sim f(\text{LSW}) = \text{LSW} / 3$  (Zhang et al. 2023)
- $\sigma_{\text{dyn, clim}}$  : Long-term (climatological) mean of the dynamic observation error (for each height and latitude bin)  $= \sqrt{\overline{\sigma_{\text{dyn}}^2}}$

## Static vs. Profile-dependent bending angle observation errors

A single profile

Long-term average



- Red:** Original static observation error
- Blue:** Long-term mean of the dynamic observation error
- Gray:** The profile-dependent observation error
- Yellow:** Dynamic observation error  $\sim \text{LSW}/3$
- Black:** The average of the profile-dependent observation error

### Main properties:

- The long-term average of the profile-dependent observation error variance always converges to traditional (statistically determined) static observation error variance.
- [If the upper-level LSW values are zero, then] Upper-level RO data use exactly the static observation errors (i.e., not profile-dependent).
- The observation errors of lower-level RO data are largely determined by their LSW values.

\* Before defining the error model, the LSW values were artificially reduced to zero linearly from 9 to 12 km and set to zero above 12 km.

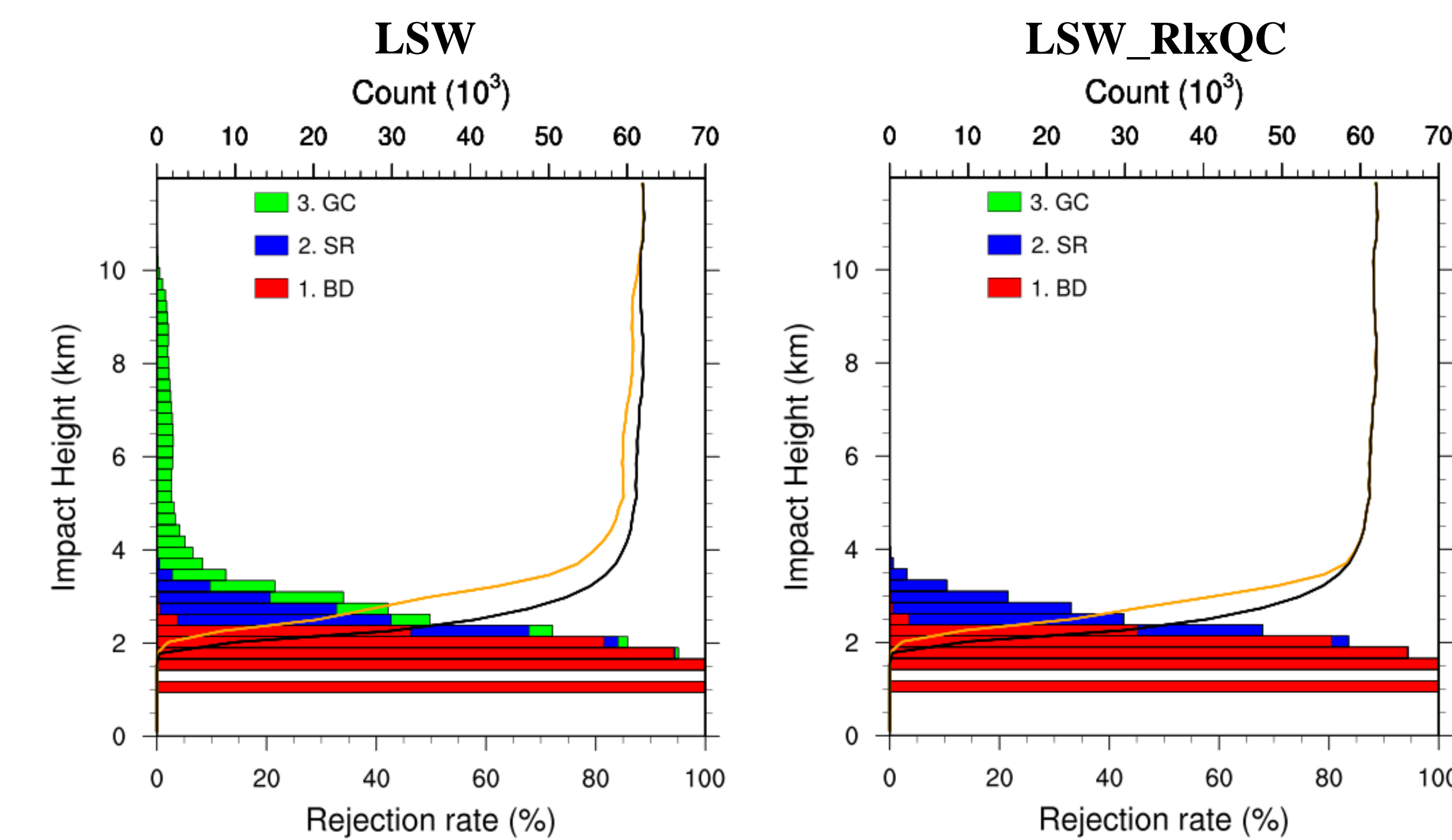
## Experimental design

Model: CWA TGFS (an NCEP GFS-GSI-based system)  
Period: 1 September – 15 October 2021

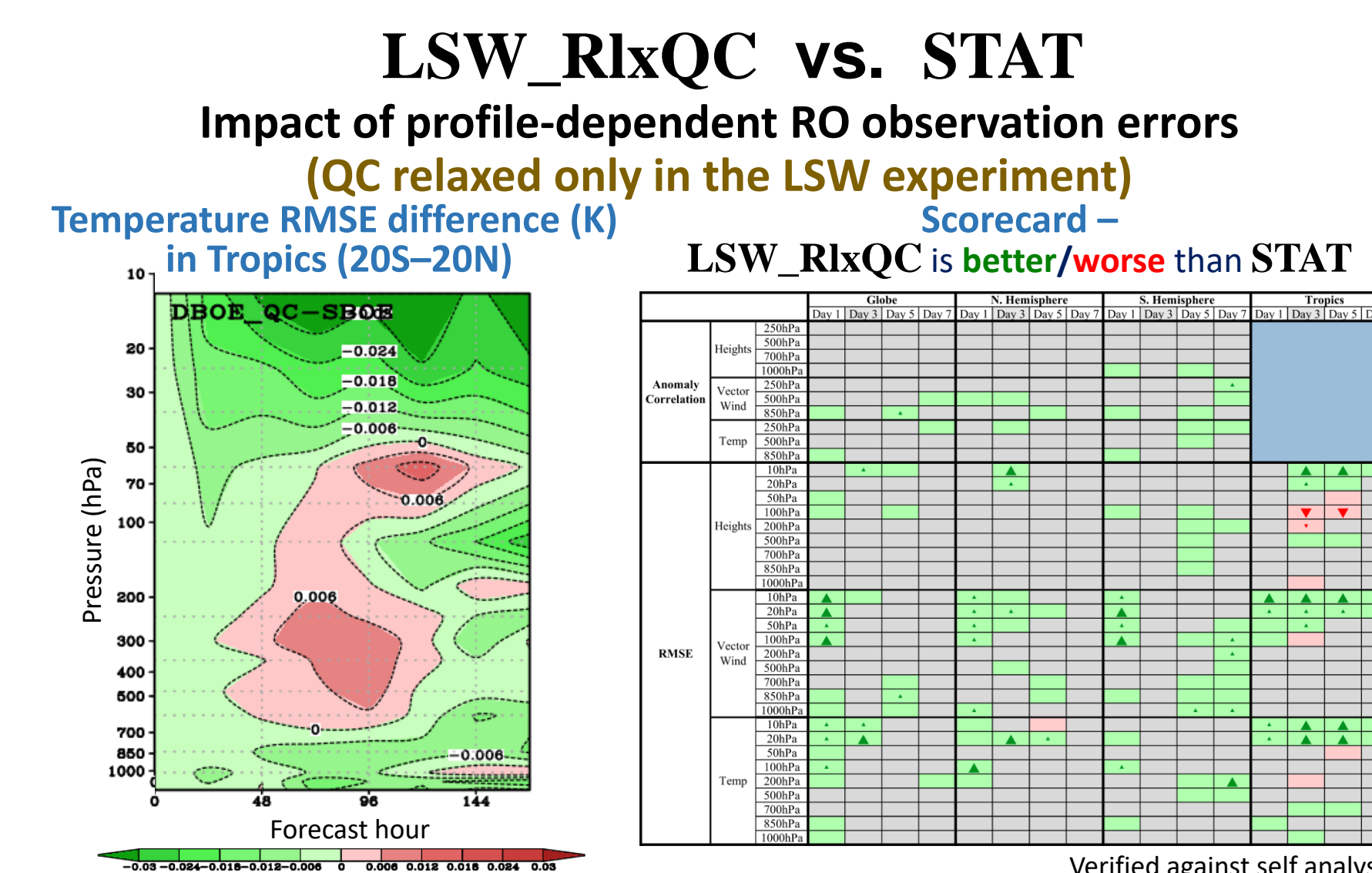
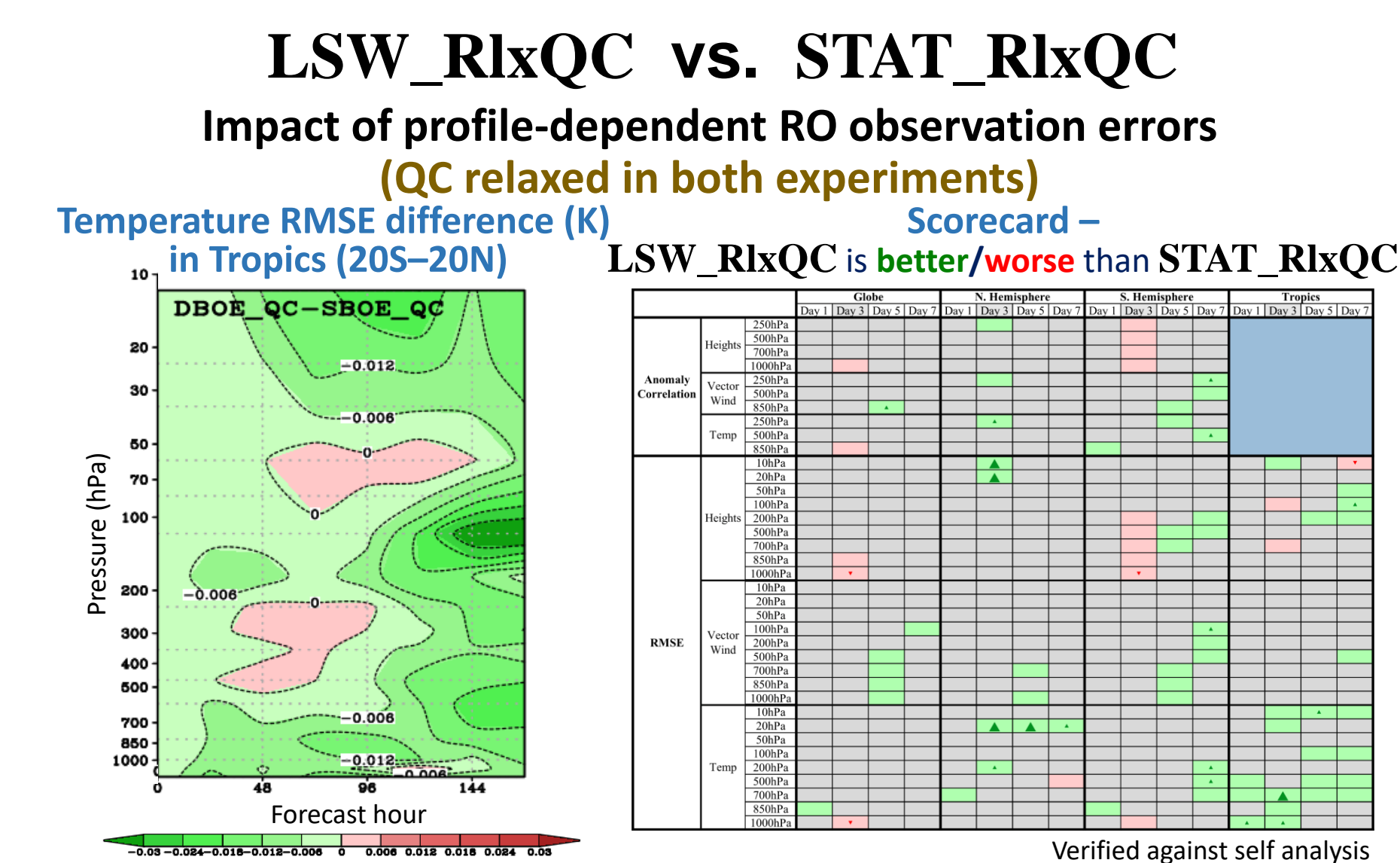
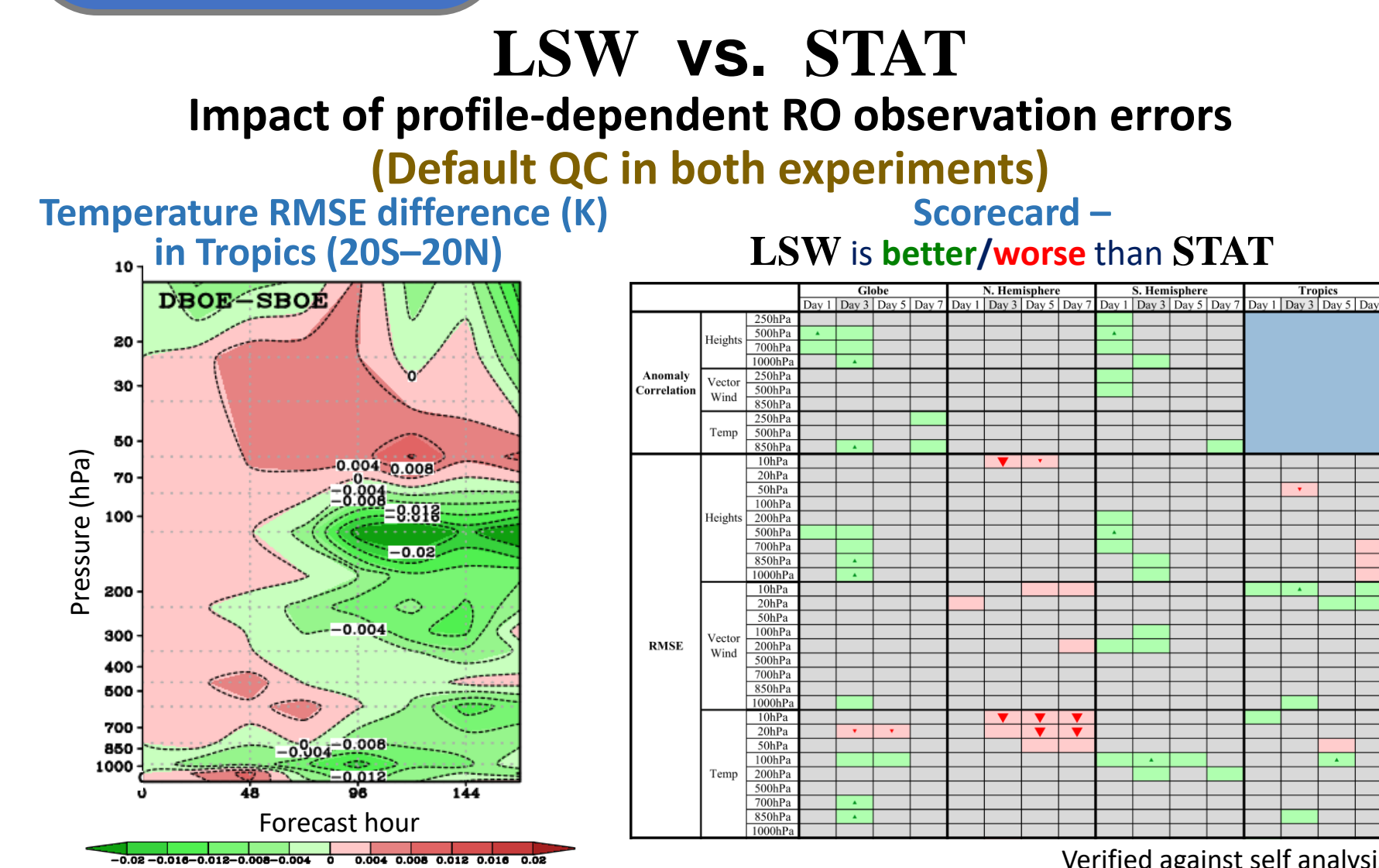
Experiment	LSW-based observation error model*	RO quality control
STAT	–	GSI-default QC
LSW	✓	GSI-default QC
STAT_RlxQC	–	Do not use "statistical gross error check"
LSW_RlxQC	✓	Do not use "statistical gross error check"

\* The LSW-based observation error model is only applied to FORMOSAT-7/COSMIC-2 RO data.

## Observation counts & rejection rates



## Results



## Conclusion and future work

- We propose a new approach to formulate a bending angle observation error model, which considers both the traditional (statistically determined) static observation errors and the LSW-determined dynamic observation errors.
- We test this new profile-dependent RO observation error model in CWA TGFS global NWP system:
  - When QC is unchanged, it improves slightly some forecast skills.
  - When it is combined with a relaxation of the GSI-default QC, a larger positive impact is found.
- This approach provides a general procedure to develop profile-dependent RO observation error models upon any statistically determined RO observation error formula.
- In the current study, we apply this profile-dependent RO observation error model only to FORMOSAT-7/COSMIC-2 RO data. We will apply this observation error model to ALL ROMEX data once the UCAR-processed ROMEX data (with LSW values included) are released.

## References

- Li et al., 8th ROM SAF Workshop June 11-13, 2024, <https://ecmwfevents.com/assets/presentations/romsaf-li1718187954.pdf>
- Liu et al., 2018, *J. Atmos. Oceanic Technol.*, **35**, 2117–2131, <https://doi.org/10.1175/JTECH-D-17-0224.1>.
- Sjoberg et al., 2023, *J. Atmos. Oceanic Technol.*, **40**, 1461–1474, <https://doi.org/10.1175/JTECH-D-23-0029.1>.
- Zhang et al., 2023, *Mon. Wea. Rev.*, **151**, 589–601, <https://doi.org/10.1175/MWR-D-22-0122.1>.